



aMC@NLO





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LO
predictions





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NLO
corrections





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LO
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• The parton-level cross section can be computed as a series in perturbation theory, using the coupling constant as an expansion parameter, schematically:



 Including higher corrections improves predictions and reduces theoretical uncertainties





$$d\sigma = \sum_{a,b} \int dx_1 dx_2 \ f_a(x_1, \mu_F) f_b(x_2, \mu_F) d\hat{\sigma}_{ab \to X}(\hat{s}, \mu_F, \mu_R)$$
$$\hat{\sigma} = \sigma^{\text{Born}} \left(1 + \frac{\alpha_s}{2\pi} \sigma^{(1)} + \left(\frac{\alpha_s}{2\pi}\right)^2 \sigma^{(2)} + \left(\frac{\alpha_s}{2\pi}\right)^3 \sigma^{(3)} + \dots \right)$$

- Leading Order predictions can depend strongly on the renormalization and factorization scales
- Including higher order corrections reduces the dependence on these scales





- At NLO the dependence on the renormalization and factorization scales is reduced
 - First order where scale dependence in the running coupling and the PDFs is compensated for via the loop corrections: first reliable estimate of the total cross section
 - Better description of final state: impact of extra radiation included (e.g. jets can have substructure)
 - Opening of additional initial state partonic channels



 $\hat{\sigma}_{ab\to X} = \sigma_0 + \alpha_S \sigma_1 + \alpha_S^2 \sigma_2 + \dots$

- NNLO is the current state-of-the-art. There are only a few results available: Higgs, Drell-Yan, ttbar
- Why do we need it?
 - control of the uncertainties in a calculation
 - It is "mandatory" if NLO corrections are very large to check the behavior of the perturbative series
- → It is needed for Standard Candles
 µ/№
 and very precise tests of perturbation theory, exploiting
 all the available information, e.g. for determining NNLO
 Wednesday 2 May 2012
 PDF sets









- LO calculation is not reliable,
- but the perturbative series stabilizes at NNLO
- NLO estimation of the uncertainties (by scale variation) works reasonably well







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Let's focus on NLO





- NLO corrections have three parts:
 - → The Born contribution, i.e. the Leading order.
 - Virtual (or Loop) corrections: formed by an amplitude with a closed loop of particles interfered with the Born amplitudes
 - Real emission corrections: formed by amplitudes with one extra parton compared to the Born process
- Both Virtual and Real emission have one power of α_s extra compared to the Born process

$$\sigma^{\rm NLO} = \int_m d\sigma^B + \int_m d\sigma^V + \int_{m+1} d\sigma^R$$



NLO predictions









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Difficulties





- Multiple steps
 - ➡ Fix divergencies
 - Virtual amplitudes: how to compute the loops automatically in a reasonable amount of time
 - How to deal with infra-red behavior for phase-space integration
 - How to match these processes to a parton shower without double counting





$$\sigma^{\rm NLO} \sim \int d^4 \Phi_m \, B(\Phi_m) + \int d^4 \Phi_m \int_{\rm loop} d^d l \, V(\Phi_m) + \int d^d \Phi_{m+1} \, R(\Phi_{m+1})$$

- The KLN theorem tells us that divergences from virtual and real-emission corrections cancel in the sum for observables insensitive to soft and collinear radiation ("IR-safe observables")
- When doing an analytic calculation in dimensional regularization this can be explicitly seen in the cancellation of the $1/\epsilon$ and $1/\epsilon^2$ terms (with ϵ the regulator, $\epsilon \rightarrow 0$)

- Infrared safe observables Durham

- For an observable to be calculable in fixed-order perturbation theory, the observable should be infrared safe, i.e., it should be insensitive to the emission of soft or collinear partons.
- In particular, if p_i is a momentum occurring in the definition of an observable, it most be invariant under the branching p_i → p_j + p_k,
 whenever p_i and p_k are collinear or one of them is soft.
- Examples
 - "The number of gluons" produced in a collision is not an infrared safe observable
 - "The number of hard jets defined using the k_T algorithm with a transverse momentum above 40 GeV," produced in a collision is an infrared safe observable





• Are all (IR-safe) observables that we can compute using a NLO code correctly described at NLO? Suppose we have a NLO code for $pp \rightarrow ttbar$



- ➡ Total cross section
- Transverse momentum of the top quark
- Transverse momentum of the top-antitop pair
- ➡ Transverse momentum of the jet
- Top-antitop invariant mass
- ➡ Azimuthal distance between the top and anti-top



NLO...?



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X





Loop Computation



one-loop integral





 $D_i = (l + p_i)^2 - m_i^2$





- Any one-loop integral can be decomposed in scalar integrals
- The task is to find these coefficients efficiently (analytically or numerically)

Basis of scalar integrals

$$\mathcal{M}^{1\text{-loop}} = \sum_{i_0 < i_1 < i_2 < i_3} d_{i_0 i_1 i_2 i_3} \operatorname{Box}_{i_0 i_1 i_2 i_3} \\ + \sum_{i_0 < i_1 < i_2} c_{i_0 i_1 i_2} \operatorname{Triangle}_{i_0 i_1 i_2} \\ + \sum_{i_0 < i_1} b_{i_0 i_1} \operatorname{Bubble}_{i_0 i_1} \\ + \sum_{i_0} a_{i_0} \operatorname{Tadpole}_{i_0} \\ + R + \mathcal{O}(\epsilon) \\ \end{array}$$

 The a, b, c, d and R coefficients depend only on external parameters and momenta

 $D_{i} = (l + p_{i})^{2} - m_{i}^{2}$ $Tadpole_{i_{0}} = \int d^{d}l \frac{1}{D_{i_{0}}}$ $Bubble_{i_{0}i_{1}} = \int d^{d}l \frac{1}{D_{i_{0}}D_{i_{1}}}$ $riangle_{i_{0}i_{1}i_{2}} = \int d^{d}l \frac{1}{D_{i_{0}}D_{i_{1}}D_{i_{2}}}$ $Box_{i_{0}i_{1}i_{2}i_{3}} = \int d^{d}l \frac{1}{D_{i_{0}}D_{i_{1}}D_{i_{2}}}$

 All these scalar integrals are known and available in computer libraries (FF [v. Oldenborgh], QCDLoop [Ellis, Zanderighi], OneLOop [v. Hameren])


Divergences



$$\mathcal{M}^{1\text{-loop}} = \sum_{i_0 < i_1 < i_2 < i_3} d_{i_0 i_1 i_2 i_3} \operatorname{Box}_{i_0 i_1 i_2 i_3} \qquad D_i = (l+p_i)^2 - m_i^2$$

$$+ \sum_{i_0 < i_1 < i_2} c_{i_0 i_1 i_2} \operatorname{Triangle}_{i_0 i_1 i_2} \qquad \operatorname{Tadpole}_{i_0} = \int d^d l \frac{1}{D_{i_0}}$$

$$\operatorname{Bubble}_{i_0 i_1} = \int d^d l \frac{1}{D_{i_0} D_{i_1}}$$

$$\operatorname{Triangle}_{i_0 i_1 i_2} = \int d^d l \frac{1}{D_{i_0} D_{i_1} D_{i_2}}$$

$$\operatorname{Hox}_{i_0} \operatorname{Tadpole}_{i_0} \qquad \operatorname{Box}_{i_0 i_1 i_2 i_3} = \int d^d l \frac{1}{D_{i_0} D_{i_1} D_{i_2}}$$

$$\operatorname{Hox}_{i_0 i_1 i_2 i_3} = \int d^d l \frac{1}{D_{i_0} D_{i_1} D_{i_2} D_{i_3}}$$

- The coefficients d, c, b and a are finite and do not contain poles in $1/\epsilon$
- The I/ ϵ dependence is in the scalar integrals (and the UV renormalization)
- When we have solved this system (and included the UV renormalization) we have the full dependence on the soft/collinear divergences in terms of coefficients in front of the poles. These divergences should cancel against divergences in the real emission corrections (according to KLN theorem)

Virtual
$$\sim v_0 + \frac{v_1}{\epsilon} + \frac{v_2}{\epsilon^2}$$





• The decomposition to scalar integrals presented before works at the level of the integrals

$$\begin{split} \mathcal{M}^{1\text{-loop}} &= \sum_{i_0 < i_1 < i_2 < i_3} d_{i_0 i_1 i_2 i_3} \operatorname{Box}_{i_0 i_1 i_2 i_3} \\ &+ \sum_{i_0 < i_1 < i_2} c_{i_0 i_1 i_2} \operatorname{Triangle}_{i_0 i_1 i_2} \\ &+ \sum_{i_0 < i_1} b_{i_0 i_1} \operatorname{Bubble}_{i_0 i_1} \\ &+ \sum_{i_0} a_{i_0} \operatorname{Tadpole}_{i_0} \\ &+ R + \mathcal{O}(\epsilon) \end{split}$$





- The decomposition to scalar integrals presented before works at the level of the integrals
- If we would know a similar relation at the integrand level, we would be able to manipulate the integrands and extract the coefficients without doing the integrals

$$\mathcal{M}^{1\text{-loop}} = \sum_{i_0 < i_1 < i_2 < i_3} d_{i_0 i_1 i_2 i_3} \operatorname{Box}_{i_0 i_1 i_2 i_3}$$
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$$+ \frac{R}{2} + \mathcal{O}(\epsilon)$$





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$$+ R + \mathcal{O}(\epsilon)$$

$$\begin{split} N(l) &= \sum_{i_0 < i_1 < i_2 < i_3}^{m-1} \left[d_{i_0 i_1 i_2 i_3} + \tilde{d}_{i_0 i_1 i_2 i_3}(l) \right] \prod_{i \neq i_0, i_1, i_2, i_3}^{m-1} D_i \\ &+ \sum_{i_0 < i_1 < i_2}^{m-1} \left[c_{i_0 i_1 i_2} + \tilde{c}_{i_0 i_1 i_2}(l) \right] \prod_{i \neq i_0, i_1, i_2}^{m-1} D_i \\ &+ \sum_{i_0 < i_1}^{m-1} \left[b_{i_0 i_1} + \tilde{b}_{i_0 i_1}(l) \right] \prod_{i \neq i_0, i_1}^{m-1} D_i \\ &+ \sum_{i_0}^{m-1} \left[a_{i_0} + \tilde{a}_{i_0}(l) \right] \prod_{i \neq i_0}^{m-1} D_i \\ &+ \tilde{P}(l) \prod_{i}^{m-1} D_i \end{split}$$





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Spurious term







To solve the OPP reduction, choosing special values for the loop momenta helps a lot

For example, choosing *l* such that

$$D_0(\mathbf{l}^{\pm}) = D_1(\mathbf{l}^{\pm}) = D_2(\mathbf{l}^{\pm}) = D_3(\mathbf{l}^{\pm}) = 0$$

sets all the terms in this equation to zero except the first line

There are two (complex) solutions to this equation due to the quadratic nature of the propagators







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- For each phase-space point we have to solve the system of equations
- Due to the fact that the system reduces when picking special values for the loop momentum, the system greatly reduces
- We can decompose the system at the level of the squared matrix element, amplitude, diagram or anywhere in between. As long as we provide the corresponding numerator function. Since each reduction with CutTools is computationally heavy, we directly reduce the squared element with MadGraph.
- For a given phase-space point, we have to compute the numerator function several times (~50 or so for a box loop)

- Complications in d dimensions

- In the previous consideration I was very sloppy in considering if we are working in 4 or d dimensions
- In general, external momenta and polarization vectors are in 4 dimensions; only the loop momentum is in d dimensions
- To be more correct, we compute the integral

$$\int d^{d}l \frac{N(l,\tilde{l})}{\bar{D}_{0}\bar{D}_{1}\bar{D}_{2}\cdots\bar{D}_{m-1}} \qquad \begin{bmatrix} \bar{l} = l + \tilde{l} \\ \uparrow & \uparrow & \uparrow \\ d \dim & 4 \dim & \text{epsilon dim} \end{bmatrix}$$
$$\bar{D}_{i} = (\bar{l} + p_{i})^{2} - m_{i}^{2} = (l + p_{i})^{2} - m_{i}^{2} + \tilde{l}^{2} = D_{i} + \tilde{l}^{2}$$
$$\bar{l} \cdot \tilde{l} = 0 \qquad \bar{l} \cdot p_{i} = l \cdot p_{i} \qquad \bar{l} \cdot \bar{l} = l \cdot l + \tilde{l} \cdot \tilde{l}$$





$$\sum_{\substack{0 \le i_0 < i_1 < i_2 < i_3}}^{m-1} d(i_0 i_1 i_2 i_3) \int d^d \bar{\ell} \frac{1}{\bar{D}_{i_0} \bar{D}_{i_1} \bar{D}_{i_2} \bar{D}_{i_3}} \\ + \sum_{\substack{0 \le i_0 < i_1 < i_2}}^{m-1} c(i_0 i_1 i_2) \int d^d \bar{\ell} \frac{1}{\bar{D}_{i_0} \bar{D}_{i_1} \bar{D}_{i_2}} \\ + \sum_{\substack{0 \le i_0 < i_1}}^{m-1} b(i_0 i_1) \int d^d \bar{\ell} \frac{1}{\bar{D}_{i_0} \bar{D}_{i_1}} \\ + \sum_{\substack{i_0 = 0}}^{m-1} a(i_0) \int d^d \bar{\ell} \frac{1}{\bar{D}_{i_0}} \\ + R.$$

- The decomposition in terms of scalar integrals has to be done in d dimensions
- This is why the rational part R is needed





$R = R_1 + R_2$

Mattelaer Olívier





- In the OPP method, they are split into two contributions, generally called $R = R_1 + R_2$
- Both have their origin in the UV part of the model, but only R₁ can be directly computed in the OPP reduction and is given by the CutTools program





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 - Cut the Loop and use HELAS (with no denominator)
 - ➡ Generic
 - recycling







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- Need to upgrade MadGraph so to generate loop diagrams and numerical code for the integrand N(q)



$$\mathcal{N}(l^{\mu})$$





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OpenLoop: [S. Pozzorini & al.(2011)]



$$\mathcal{N}(l^{\mu}) = \sum_{r=0}^{r_{max}} C^{(r)}_{\mu_0\mu_1\cdots\mu_r} l^{\mu_0} l^{\mu_1}\cdots l^{\mu_r}$$

coefficient computed iteratively by ALOHA





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$$\mathcal{N}(l^{\mu}) = \sum_{r=0}^{r_{max}} C^{(r)}_{\mu_0\mu_1\cdots\mu_r} l^{\mu_0} l^{\mu_1}\cdots l^{\mu_r}$$
5-10 times faster

coefficient computed iteratively by ALOHA





FKS

phase-space integration

$$\sigma^{\rm NLO} \sim \int d^4 \Phi_m \, B(\Phi_m) + \int d^4 \Phi_m \int_{\rm loop} d^d l \, V(\Phi_m) + \int d^d \Phi_{m+1} \, R(\Phi_{m+1})$$

- For complicated processes we have to result to numerical phasespace integration techniques ("Monte Carlo integration"), which can only be performed in an integer number of dimensions
 - Cannot use a finite value for the dimensional regulator and take the limit to zero in a numerical code
- But we still have to cancel the divergences explicitly
- Use a subtraction method to explicitly factor out the divergences from the phase-space integrals

I skipped this interesting topic here!

NLO+PS MATCHING



- I. Fixed order calculation
- 2. Computationally expensive
- 3. Limited number of particles
- 4. Valid when partons are hard and well separated
- 5. Quantum interference correct
- 6. Needed for multi-jet description





- I. Resums logs to all orders
- 2. Computationally cheap
- 3. No limit on particle multiplicity
- 4. Valid when partons are collinear and/or soft
- 5. Partial interference through angular ordering
- 6. Needed for hadronization

Approaches are complementary: merge them!

Difficulty: avoid double counting, ensure smooth distributions

NLO+PS MATCHING



TASI 2013, Boulder CO



Matching NLO



• At NLO one faces even more severe double-counting issues:



• And also part of the virtual contribution is double counted through the definition of the Sudakov factor Δ

MC@NLO POWHEG 1. PSMC independent 1. PSMC dependent 2. Only positive unit weight 2. Some negative weighted events 3. Quantum interference exact

- 4. Used by both MG5_aMC and Sherpa.
- 3. Can use existing NLO results via the POWHEG-Box
- 4. Used by HELAC



Double counting



- The Sudakov factor Δ (which is responsible for the resummation of all the radiation in the shower) is the noemission probability
- It's defined to be $\Delta = 1 P$, where P is the probability for a branching to occur
- By using this conservation of probability in this way, Δ contains contributions from the virtual corrections implicitly
- Because at NLO the virtual corrections are already included via explicit matrix elements, Δ is double counting with the virtual corrections
- In fact, because the shower is unitary, what we are double counting in the real emission corrections is exactly equal to what we are double counting in the virtual corrections (but with opposite sign)!





[Frixione & Webber (2002)]

• To remove the double counting, we can add and subtract the same term to the *m* and *m*+1 body configurations

$$\frac{d\sigma_{\rm NLOwPS}}{dO} = \left[d\Phi_m (B + \int_{\rm loop} V + \int d\Phi_1 MC) \right] I_{\rm MC}^{(m)}(O) + \left[d\Phi_{m+1} (R - MC) \right] I_{\rm MC}^{(m+1)}(O)$$

Where the *MC* are defined to be the contribution of the parton shower to get from the *m* body Born final state to the *m*+1 body real emission final state







$$\frac{d\sigma_{\rm NLOwPS}}{dO} = \left[d\Phi_m (B + \int_{\rm loop} V + \int d\Phi_1 MC) \right] I_{\rm MC}^{(m)}(O) + \left[d\Phi_{m+1} (R - MC) \right] I_{\rm MC}^{(m+1)}(O)$$

- We generate events for the two terms between the square brackets (S- and H-events) separately
- There is no guarantee that these contributions are separately positive (even though predictions for infra-red safe observables should always be positive!)
- Therefore, when we do event unweighting we can only unweight the events **up to a sign**. These signs should be taken into account when doing a physics analysis (i.e. making plots etc.)
- The events are only physical when they are showered.











- Shower Monte Carlo
 - ➡ QCD in colinear approximation
 - ➡ key object is the Sudakov factor
- Matching/Merging at LO
 - ➡ How to use it/check it
- NLO
 - ➡ Automated for the SM
 - ➡ All observable are not NLO accurate
 - Fixed Order computation are not definite positive
 - NLO+PS events are not physical before the shower





- Never trust a code (even mine)
 - ➡ Always check!
- Never use those as full black box.