

FeynRules Implementation of Sextet_Diquarks

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Abstract

We describe the implementation of the Sextet_Diquarks model using the FeynRules package.

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1 Introduction

We describe the implementation of the Sextet_Diquarks model using the FeynRules [1] package.

2 Gauge Symmetries

The gauge group of this model is

$$U1Y \times SU2L \times SU3C. \tag{1}$$

Details of these gauge groups can be found in Table 1.

| Group | Abelian | Gauge Boson | Coupling Constant | Charge | Structure Constant | Symmetric Tensor | Reps | Defs |
|-------|---------|-------------|-------------------|--------|--------------------|------------------|--|---|
| U1Y | T | B | g1 | Y | | | | |
| SU2L | F | Wi | gw | | Eps | | $FSU2L_{k,k}$ | $FSU2L[a\$, b\$, c\$] \rightarrow -I \text{Eps}[a\$, b\$, c\$]$ |
| SU3C | F | G | gs | | f | dSUN | $T6_{u,u}$ $T_{i,i}$ $FSU3C_{a,a}$ | $FSU3C[a\$, b\$, c\$] \rightarrow -I f[a\$, b\$, c\$]$ |

Table 1: Details of gauge groups.

The definitions of the indices can be found in Table 2.

| Index | Symbol | Range |
|------------|--------|-------|
| Generation | f | 1-3 |
| Colour | i | 1-3 |
| Gluon | a | 1-8 |
| SU2W | k | 1-3 |
| Sextet | u | 1-6 |

Table 2: Definition of the indices.

3 Fields

In this section, we describe the field content of our model implementation.

3.1 Vector Fields

In this subsection, we describe the vector fields of our model. The details of the physical vectors can be found in Table 3.

| Class | SC | I | FI | QN | Mem | M | W | PDG |
|-------|----|---|----|---------|-----|--------------|------------|-----|
| A | T | | | | A | 0 | 0 | 22 |
| Z | T | | | | Z | MZ= 91.1876 | WZ= 2.4952 | 23 |
| W | F | | | $Q = 1$ | W | MW= Internal | WW= 2.085 | 24 |
| G | T | a | | | G | 0 | 0 | 21 |

Table 3: Details of physical vector fields. The headers are as follows: SC = self conjugate, I = indices, FI = flavor index, QN = quantum numbers, Mem = members, M = mass, W = width, and PDG = particle data group number.

The details of the unphysical vectors can be found in Table 4.

| Class | SC | I | FI | QN | Mem | Definitions |
|-------|----|---|----|----|-----|---|
| Wi | T | k | k | | Wi | $Wi_{\mu,1} \rightarrow \frac{W_{\mu} + W_{\mu}^{\dagger}}{\sqrt{2}}$ $Wi_{\mu,2} \rightarrow -\frac{i(-W_{\mu} + W_{\mu}^{\dagger})}{\sqrt{2}}$ $Wi_{\mu,3} \rightarrow s_w A_{\mu} + c_w Z_{\mu}$ |
| B | T | | | | B | $B_{\mu} \rightarrow c_w A_{\mu} - s_w Z_{\mu}$ |

Table 4: Details of unphysical vector fields. The headers are as follows: SC = self conjugate, I = indices, FI = flavor index, QN = quantum numbers, and Mem = members.

3.2 Fermion Fields

In this subsection, we describe the fermion fields of our model. The details of the physical fermions can be found in Table 5.

3.3 Scalar Fields

In this subsection, we describe the scalar fields of our model. The details of the physical scalars can be found in Table 6.

3.4 Ghost Fields

In this subsection, we describe the ghost fields of our model. The details of the physical ghosts can be found in Table 7. The details of the unphysical ghosts can be found in Table 8.

| Class | SC | I | FI | QN | Mem | M | W | PDG |
|-------|----|------|----|--------------------------------|-----|--------------------|-------------|-----|
| vl | F | f | f | $LeptonNumber = 1$ | ve | | | 12 |
| | | | | | vm | | | 14 |
| | | | | | vt | | | 16 |
| l | F | f | f | $Q = -1$ $LeptonNumber = 1$ | e | MI Me= 0.000511 | | 11 |
| | | | | | m | MM= 0.10566 | | 13 |
| | | | | | tt | MTA= 1.777 | | 15 |
| uq | F | f, i | f | $Q = 2/3$ | | Mu | | |
| | | | | | u | MU= 0.00255 | 0 | 2 |
| | | | | | c | MC= 1.42 | 0 | 4 |
| | | | | | t | MT= 172 | WT= 1.50834 | 6 |
| dq | F | f, i | f | $Q = -1/3$ | | Md | | |
| | | | | | d | MD= 0.00504 | | 1 |
| | | | | | s | MS= 0.101 | | 3 |
| | | | | | b | MB= 4.7 | | 5 |

Table 5: Details of physical fermion fields. The headers are as follows: SC = self conjugate, I = indices, FI = flavor index, QN = quantum numbers, Mem = members, M = mass, W = width, and PDG = particle data group number.

| Class | SC | I | FI | QN | Mem | M | W | PDG |
|-------|----|---|----|--------------------------|------|--------------|----------------|-----|
| H | T | | | | H | MH= 120 | WH= 0.00575309 | 25 |
| phi | T | | | | phi | MZ= 91.1876 | Wphi | 250 |
| phi2 | F | | | $Q = 1$ | phi2 | MW= Internal | Wphi2 | 251 |
| six1 | F | u | | $Q = 1/3$ $Y = 1/3$ | six1 | MSIX1= 500 | WSIX1= 4.4108 | |
| six2 | F | u | | $Q = -2/3$ $Y = -2/3$ | six2 | MSIX2= 500 | WSIX2= 4.774 | |
| six3 | F | u | | $Q = 4/3$ $Y = 4/3$ | six3 | MSIX3= 500 | WSIX3= 4.0647 | |

Table 6: Details of physical scalar fields. The headers are as follows: SC = self conjugate, I = indices, FI = flavor index, QN = quantum numbers, Mem = members, M = mass, W = width, and PDG = particle data group number.

| Class | SC | I | FI | QN | Mem | M | W | PDG |
|-------|----|---|----|-------------------|------|--------------|---|-----|
| ghA | F | | | $GhostNumber = 1$ | ghA | 0 | | |
| ghZ | F | | | $GhostNumber = 1$ | ghZ | MZ= 91.1876 | | |
| ghWp | F | | | $Q = 1$ | ghWp | MW= Internal | | |
| ghWm | F | | | $Q = -1$ | ghWm | MW= Internal | | |
| ghG | F | a | | $GhostNumber = 1$ | ghG | 0 | | |

Table 7: Details of physical ghost fields. The headers are as follows: SC = self conjugate, I = indices, FI = flavor index, QN = quantum numbers, Mem = members, M = mass, W = width, and PDG = particle data group number.

| Class | SC | I | FI | QN | Mem | Definitions |
|-------|----|---|----|----|------|---|
| ghWi | F | k | k | | ghWi | $\text{ghWi}_1 \rightarrow \frac{\text{ghWm} + \text{ghWp}}{\sqrt{2}}$ $\text{ghWi}_2 \rightarrow -\frac{i(\text{ghWm} - \text{ghWp})}{\sqrt{2}}$ $\text{ghWi}_3 \rightarrow c_w \text{ghZ} + \text{ghA}_{s_w}$ |
| ghB | F | | | | ghB | $\text{ghB} \rightarrow c_w \text{ghA} - \text{ghZ}_{s_w}$ |

Table 8: Details of unphysical ghost fields. The headers are as follows: SC = self conjugate, I = indices, FI = flavor index, QN = quantum numbers, and Mem = members.

4 Lagrangian

In this section, we describe the Lagrangian of our model implementation.

4.1 L_1

$$-\frac{1}{4}(-\partial_\nu[B_\mu] + \partial_\mu[B_\nu])^2 - \frac{1}{4}(-\partial_\nu[G_{\mu,a1}] + \partial_\mu[G_{\nu,a1}] + g_s f_{a1,a2,a3} G_{\mu,a2} G_{\nu,a3})(-\partial_\nu[G_{\mu,a1}] + \partial_\mu[G_{\nu,a1}] + g_s f_{a1,a4,a5} G_{\mu,a4} G_{\nu,a5}) - \frac{1}{4}(-\partial_\nu[Wi_{\mu,i1}] + \partial_\mu[Wi_{\nu,i1}] + g_w \epsilon_{i1,i2,i3} Wi_{\mu,i2} Wi_{\nu,i3})(-\partial_\nu[Wi_{\mu,i1}] + \partial_\mu[Wi_{\nu,i1}] + g_w \epsilon_{i1,i4,i5} Wi_{\mu,i4} Wi_{\nu,i5})$$

4.2 L_2

$$\mu^2 (\text{phi2phi2}^\dagger + \frac{1}{2}(H - i\phi + v)(H + i\phi + v)) - (\text{phi2phi2}^\dagger + \frac{1}{2}(H - i\phi + v)(H + i\phi + v))^2 \lambda + \left(-\frac{i\text{ephi2}B_\mu}{2c_w} + \partial_\mu[\text{phi2}] + \frac{e\left(\frac{(H+i\phi+v)(Wi_{\mu,1}-iWi_{\mu,2})}{\sqrt{2}} - i\text{phi2}Wi_{\mu,3}\right)}{2s_w} \right) \left(\frac{i\text{ephi2}^\dagger B_\mu}{2c_w} + \partial_\mu[\text{phi2}^\dagger] + \frac{e\left(\frac{(H-i\phi+v)(Wi_{\mu,1}+iWi_{\mu,2})}{\sqrt{2}} + i\text{phi2}^\dagger Wi_{\mu,3}\right)}{2s_w} \right) + \left(\frac{e(H-i\phi+v)B_\mu}{2\sqrt{2}c_w} - \frac{i(\partial_\mu[H]-i\partial_\mu[\phi])}{\sqrt{2}} + \frac{e(i\text{phi2}^\dagger(Wi_{\mu,1}-iWi_{\mu,2}) - \frac{(H-i\phi+v)Wi_{\mu,3}}{\sqrt{2}})}{2s_w} \right) \left(\frac{e(H+i\phi+v)B_\mu}{2\sqrt{2}c_w} + \frac{i(\partial_\mu[H]+i\partial_\mu[\phi])}{\sqrt{2}} + \frac{e(-i\text{phi2}(Wi_{\mu,1}+iWi_{\mu,2}) - \frac{(H-i\phi+v)Wi_{\mu,3}}{\sqrt{2}})}{2s_w} \right)$$

4.3 L_3

$$i\bar{d}q.\gamma^\mu.\partial_\mu[dq] + i\bar{l}.\gamma^\mu.\partial_\mu[l] + i\bar{u}q.\gamma^\mu.\partial_\mu[uq] + i\bar{v}l.\gamma^\mu.\partial_\mu[v] + \frac{eB_\mu\bar{d}q.\gamma^\mu.P_-.dq}{6c_w} - \frac{eB_\mu\bar{d}q.\gamma^\mu.P_+.dq}{3c_w} - \frac{eB_\mu\bar{l}.\gamma^\mu.P_-.l}{2c_w} - \frac{eB_\mu\bar{l}.\gamma^\mu.P_+.l}{c_w} + \frac{eB_\mu\bar{u}q.\gamma^\mu.P_-.uq}{6c_w} + \frac{2eB_\mu\bar{u}q.\gamma^\mu.P_+.uq}{3c_w} - \frac{eB_\mu\bar{v}l.\gamma^\mu.P_-.vl}{2c_w} + g_s \left(\bar{d}q.T^a.\gamma^\mu.dq + \bar{u}q.T^a.\gamma^\mu.uq \right) G_{\mu,a} + \frac{e\left(\sqrt{2}\bar{v}l.\gamma^\mu.P_-.lW_\mu + \sqrt{2}\bar{u}q.CKM.\gamma^\mu.P_-.dqW_\mu + \sqrt{2}\bar{l}.\gamma^\mu.P_-.vlW_\mu^\dagger + \sqrt{2}\bar{d}q.CKM^\dagger.\gamma^\mu.P_-.uqW_\mu^\dagger - \bar{d}q.\gamma^\mu.P_-.dqWi_{\mu,3} - \bar{l}.\gamma^\mu.P_-.lWi_{\mu,3} + \bar{u}q.\gamma^\mu.P_-.uqWi_{\mu,3} + \bar{v}l.\gamma^\mu.P_-.vlWi_{\mu,3}\right)}{2s_w}$$

4.4 L_4

$$i\text{phi2CKM}_{n\$1406,m\$1406}\bar{u}q_{s\$1406,n\$1406,i\$1406}.dq_{r\$1406,m\$1406,i\$1406}.P_{+s\$1406,r\$1406}y^d_{m\$1406} - i\text{phi2}^\dagger\text{CKM}_{n\$1407,m\$1407}\bar{d}q_{r\$1408,m\$1407,i\$1407}.uq_{r\$1409,n\$1407,i\$1407}.P_{-r\$1408,r\$1409}y^d_{m\$1407} - \frac{(H+i\phi+v)\bar{d}q_{s\$1406,n\$1406,i\$1406}.dq_{r\$1406,n\$1406,i\$1406}.P_{+s\$1406,r\$1406}y^d_{n\$1406}}{\sqrt{2}} - \frac{(H-i\phi+v)\bar{d}q_{r\$1410,n\$1407,i\$1407}.dq_{r\$1411,n\$1407,i\$1407}.P_{-r\$1410,r\$1411}y^d_{n\$1407}}{\sqrt{2}} - \frac{(H+i\phi+v)\bar{l}_{r\$1406,n\$1406}.l_{r\$1406,n\$1406}.P_{+s\$1406,r\$1406}y^l_{n\$1406}}{\sqrt{2}} + i\text{phi2}\bar{v}l_{s\$1406,n\$1406}.l_{r\$1406,n\$1406}.P_{+s\$1406,r\$1406}y^l_{n\$1406} - \frac{(H-i\phi+v)\bar{l}_{r\$1412,n\$1407}.l_{r\$1413,n\$1407}.P_{-r\$1412,r\$1413}y^l_{n\$1407}}{\sqrt{2}} - i\text{phi2}^\dagger\bar{l}_{r\$1414,n\$1407}.vl_{r\$1415,n\$1407}.P_{-r\$1414,r\$1415}y^l_{n\$1407} + i\text{phi2}^\dagger\text{CKM}_{m\$1406,n\$1406}\bar{d}q_{s\$1406,n\$1406,i\$1406}.uq_{r\$1406,m\$1406,i\$1406}.P_{+s\$1406,r\$1406}y^u_{m\$1406} - i\text{phi2}\text{CKM}_{m\$1407,n\$1407}\bar{u}q_{r\$1416,m\$1407,i\$1407}.dq_{r\$1417,n\$1407,i\$1407}.P_{-r\$1416,r\$1417}y^u_{m\$1407} - \frac{(H-i\phi+v)\bar{u}q_{s\$1406,n\$1406,i\$1406}.uq_{r\$1406,n\$1406,i\$1406}.P_{+s\$1406,r\$1406}y^u_{n\$1406}}{\sqrt{2}} - \frac{(H+i\phi+v)\bar{u}q_{r\$1418,n\$1407,i\$1407}.uq_{r\$1419,n\$1407,i\$1407}.P_{-r\$1418,r\$1419}y^u_{n\$1407}}{\sqrt{2}}$$

4.5 L_5

$$2\sqrt{2} \left(\bar{d}q_{s,n,i}.uq_{r,m,j}.^C K6\text{bar}[k,i,j] \text{LUDL}_{m,n} P_{-s,r} \text{six}1_k + \bar{d}q_{s,n,i}.uq_{r,m,j}.^C K6\text{bar}[k,i,j] \text{LQQR}_{m,n} P_{+s,r} \text{six}1_k \right) - \text{MSIX}1^2 \text{six}1_k \text{six}1_k^\dagger + \text{LHS1} (\text{phi2phi2}^\dagger + \frac{1}{2}(H - i\phi + v)(H + i\phi + v)) \text{six}1_k \text{six}1_k^\dagger + 2\sqrt{2} \left(\text{LQQR}_{m,n} \bar{u}q_{r\$1428,m,j}.^C .dq_{r\$1429,n,i}.K6[k,i,j] P_{-r\$1428,r\$1429} \text{six}1_k^\dagger + \text{LUDL}_{m,n} \bar{u}q_{r\$1426,m,j}.^C .dq_{r\$1427,n,i}.K6[k,i,j] P_{+r\$1426,r\$1427} \text{six}1_k^\dagger \right) + \text{LSS1} \text{six}1_{k1} \text{six}1_{k2} \text{six}1_{k1}^\dagger \text{six}1_{k2}^\dagger + 2\sqrt{2} \bar{d}q_{s,n,i}.dq_{r,m,j}.^C K6\text{bar}[k,i,j] \text{LDDL}_{m,n} P_{-s,r} \text{six}2_k + 2\sqrt{2} \text{LDDL}_{m,n} \bar{d}q_{r\$1430,m,j}.^C .dq_{r\$1431,n,i}.K6[k,i,j] P_{+r\$1430,r\$1431} \text{six}2_k^\dagger - \text{MSIX}2^2 \text{six}2_k \text{six}2_k^\dagger + \text{LHS2} (\text{phi2phi2}^\dagger + \frac{1}{2}(H - i\phi + v)(H + i\phi + v)) \text{six}2_k \text{six}2_k^\dagger + \text{LSS122} \text{six}1_{k2} \text{six}1_{k1}^\dagger \text{six}2_{k1} \text{six}2_{k2}^\dagger +$$

$$\begin{aligned}
& \text{LSS121six1}_{k1}\text{six1}_{k1}^\dagger\text{six2}_{k2}\text{six2}_{k2}^\dagger + \text{LSS22six2}_{k1}\text{six2}_{k2}\text{six2}_{k1}^\dagger\text{six2}_{k2}^\dagger + 2\sqrt{2}\bar{u}_{q_{s,n,i}}\cdot u_{q_{r,m,j}}{}^C\text{K6bar}[k,i,j]\text{LUUL}_{m,n}P_{-s,r}\text{six3}_k + \\
& 2\sqrt{2}\text{LUUL}_{m,n}{}^*\bar{u}_{q_{r\$1432,m,j}}{}^C\cdot u_{q_{r\$1433,n,i}}{}^C\text{K6}[k,i,j]P_{+r\$1432,r\$1433}\text{six3}_k^\dagger - \text{MSIX2}^2\text{six3}_k\text{six3}_k^\dagger + \\
& \text{LHS3}(\text{phi2phi2}^\dagger + \frac{1}{2}(H - i\phi + v)(H + i\phi + v))\text{six3}_k\text{six3}_k^\dagger + \text{LSS132six1}_{k2}\text{six1}_{k1}^\dagger\text{six3}_{k1}\text{six3}_{k2}^\dagger + \\
& \text{LSS232six2}_{k2}\text{six2}_{k1}^\dagger\text{six3}_{k1}\text{six3}_{k2}^\dagger + \text{LSS131six1}_{k1}\text{six1}_{k1}^\dagger\text{six3}_{k2}\text{six3}_{k2}^\dagger + \text{LSS231six2}_{k1}\text{six2}_{k1}^\dagger\text{six3}_{k2}\text{six3}_{k2}^\dagger + \\
& \text{LSS33six3}_{k1}\text{six3}_{k2}\text{six3}_{k1}^\dagger\text{six3}_{k2}^\dagger + \\
& (\partial_\mu [\text{six1}_k^\dagger] + \frac{1}{3}ig_1B_\mu\text{six1}_k^\dagger + ig_sG_{\mu,a\$1420}\text{six1}_{i\$1420}^\dagger\text{T6}_{i\$1420,k}{}^{a\$1420}) (\partial_\mu [\text{six1}_k] - \frac{1}{3}ig_1B_\mu\text{six1}_k - ig_sG_{\mu,a\$1421}\text{six1}_{i\$1421}\text{T6}_{k,i\$1421}{}^a) \\
& (\partial_\mu [\text{six2}_k^\dagger] - \frac{2}{3}ig_1B_\mu\text{six2}_k^\dagger + ig_sG_{\mu,a\$1422}\text{six2}_{i\$1422}^\dagger\text{T6}_{i\$1422,k}{}^{a\$1422}) (\partial_\mu [\text{six2}_k] + \frac{2}{3}ig_1B_\mu\text{six2}_k - ig_sG_{\mu,a\$1423}\text{six2}_{i\$1423}\text{T6}_{k,i\$1423}{}^a) \\
& (\partial_\mu [\text{six3}_k^\dagger] + \frac{4}{3}ig_1B_\mu\text{six3}_k^\dagger + ig_sG_{\mu,a\$1424}\text{six3}_{i\$1424}^\dagger\text{T6}_{i\$1424,k}{}^{a\$1424}) (\partial_\mu [\text{six3}_k] - \frac{4}{3}ig_1B_\mu\text{six3}_k - ig_sG_{\mu,a\$1425}\text{six3}_{i\$1425}\text{T6}_{k,i\$1425}{}^a)
\end{aligned}$$

5 Parameters

In this section, we describe the parameters of our model implementation.

5.1 External Parameters

In this subsection, we describe the external parameters of our model. The details of the external parameters can be found in Tables 9, 10, 11.

| P | C | I | V | D | PN | BN | OB | IO | Description |
|----------------|---|------|--|---|-------|----------|----|---------|--|
| α_{EW1} | F | | 127.9 | | aEWM1 | SMINPUTS | | QED, -2 | Inverse of the electroweak coupling constant |
| G_f | F | | 0.0000116637 | | | SMINPUTS | | QED, 2 | Fermi constant |
| α_s | F | | 0.1184 | | aS | SMINPUTS | | QCD, 2 | Strong coupling constant at the Z pole. |
| yndo | F | | 0. | | | YUKAWA | 1 | | Down Yukawa mass |
| ymup | F | | 0. | | | YUKAWA | 2 | | Up Yukawa mass |
| yms | F | | 0. | | | YUKAWA | 3 | | Strange Yukawa mass |
| ymc | F | | 0. | | | YUKAWA | 4 | | Charm Yukawa mass |
| ymb | F | | 4.7 | | | YUKAWA | 5 | | Bottom Yukawa mass |
| ymt | F | | 172. | | | YUKAWA | 6 | | Top Yukawa mass |
| yme | F | | 0. | | | YUKAWA | 11 | | Electron Yukawa mass |
| ymm | F | | 0. | | | YUKAWA | 13 | | Muon Yukawa mass |
| ymtau | F | | 1.777 | | | YUKAWA | 15 | | Tau Yukawa mass |
| θ_c | F | | 0.227736 | | | CKMBLOCK | | | Cabibbo angle |
| LQQRR | F | f, f | LQQRR _{1,1} → 0.1 LQQRR _{1,2} → 0. LQQRR _{1,3} → 0. LQQRR _{2,1} → 0. LQQRR _{2,2} → 0.1 LQQRR _{2,3} → 0. LQQRR _{3,1} → 0. LQQRR _{3,2} → 0. LQQRR _{3,3} → 0.1 | | | | | QCD, 1 | |
| LQQRI | F | f, f | LQQRI _{1,1} → 0. LQQRI _{1,2} → 0. LQQRI _{1,3} → 0. LQQRI _{2,1} → 0. LQQRI _{2,2} → 0. LQQRI _{2,3} → 0. LQQRI _{3,1} → 0. LQQRI _{3,2} → 0. LQQRI _{3,3} → 0. | | | | | QCD, 1 | |
| LUDLR | F | f, f | LUDLR _{1,1} → 0.1 LUDLR _{1,2} → 0. LUDLR _{1,3} → 0. LUDLR _{2,1} → 0. LUDLR _{2,2} → 0.1 LUDLR _{2,3} → 0. LUDLR _{3,1} → 0. LUDLR _{3,2} → 0. | | | | | QCD, 1 | |

Table 9: Details of external parameters. The headers are as follows: P = parameter, C = complex, I = indices, V = value, D = definition, PN = parameter name, BN = block name, OB = order block, and IO = interaction order.

| P | C | I | V | D | PN | BN | OB | IO | Description |
|--------|---|------|---|---|----|----|----|--------|-------------|
| LUDLI | F | f, f | LUDLR _{3,3} → 0.1 LUDLI _{1,1} → 0. LUDLI _{1,2} → 0. LUDLI _{1,3} → 0. LUDLI _{2,1} → 0. LUDLI _{2,2} → 0. LUDLI _{2,3} → 0. LUDLI _{3,1} → 0. LUDLI _{3,2} → 0. LUDLI _{3,3} → 0. | | | | | QCD, 1 | |
| LUULR | F | f, f | LUULR _{1,1} → 0.1 LUULR _{1,2} → 0. LUULR _{1,3} → 0. LUULR _{2,1} → 0. LUULR _{2,2} → 0.1 LUULR _{2,3} → 0. LUULR _{3,1} → 0. LUULR _{3,2} → 0. LUULR _{3,3} → 0.1 | | | | | QCD, 1 | |
| LUULI | F | f, f | LUULI _{1,1} → 0. LUULI _{1,2} → 0. LUULI _{1,3} → 0. LUULI _{2,1} → 0. LUULI _{2,2} → 0. LUULI _{2,3} → 0. LUULI _{3,1} → 0. LUULI _{3,2} → 0. LUULI _{3,3} → 0. | | | | | QCD, 1 | |
| LDDLRL | F | f, f | LDDLRL _{1,1} → 0.1 LDDLRL _{1,2} → 0. LDDLRL _{1,3} → 0. LDDLRL _{2,1} → 0. LDDLRL _{2,2} → 0.1 LDDLRL _{2,3} → 0. LDDLRL _{3,1} → 0. LDDLRL _{3,2} → 0. LDDLRL _{3,3} → 0.1 | | | | | QCD, 1 | |

Table 10: Details of external parameters. The headers are as follows: P = parameter, C = complex, I = indices, V = value, D = definition, PN = parameter name, BN = block name, OB = order block, and IO = interaction order.

| P | C | I | V | D | PN | BN | OB | IO | Description |
|--------|---|------|---|---|----|----|----|--------|-------------|
| LDDLI | F | f, f | LDDLI _{1,1} → 0. LDDLI _{1,2} → 0. LDDLI _{1,3} → 0. LDDLI _{2,1} → 0. LDDLI _{2,2} → 0. LDDLI _{2,3} → 0. LDDLI _{3,1} → 0. LDDLI _{3,2} → 0. LDDLI _{3,3} → 0. | | | | | QCD, 1 | |
| LHS1 | F | | 0.1 | | | | | QED, 2 | |
| LHS2 | F | | 0.1 | | | | | QED, 2 | |
| LHS3 | F | | 0.1 | | | | | QED, 2 | |
| LSS11 | F | | 0.1 | | | | | QCD, 2 | |
| LSS121 | F | | 0.1 | | | | | QCD, 2 | |
| LSS122 | F | | 0.1 | | | | | QCD, 2 | |
| LSS131 | F | | 0.1 | | | | | QCD, 2 | |
| LSS132 | F | | 0.1 | | | | | QCD, 2 | |
| LSS22 | F | | 0.1 | | | | | QCD, 2 | |
| LSS231 | F | | 0.1 | | | | | QCD, 2 | |
| LSS232 | F | | 0.1 | | | | | QCD, 2 | |
| LSS33 | F | | 0.1 | | | | | QCD, 2 | |

Table 11: Details of external parameters. The headers are as follows: P = parameter, C = complex, I = indices, V = value, D = definition, PN = parameter name, BN = block name, OB = order block, and IO = interaction order.

5.2 Internal Parameters

In this subsection, we describe the internal parameters of our model. The details of the internal parameters can be found

| P | C | I | V | NV | D | PN | IO | Description |
|---------------|---|------|--------|--|---|--|---------|---|
| α_{EW} | F | | Eq. 2 | 0.00781861 | | aEW | QED, 2 | Electroweak coupling constant |
| M_W | F | | Eq. 3 | 79.8244 | | | | W mass |
| sw2 | F | | Eq. 4 | 0.233699 | | | | Squared Sin of the Weinberg angle |
| e | F | | Eq. 5 | 0.313451 | | | QED, 1 | Electric coupling constant |
| c_w | F | | Eq. 6 | 0.875386 | | | | Cos of the Weinberg angle |
| s_w | F | | Eq. 7 | 0.483424 | | | | Sin of the Weinberg angle |
| g_w | F | | Eq. 8 | 0.648397 | | | QED, 1 | Weak coupling constant |
| g_1 | F | | Eq. 9 | 0.358072 | | | QED, 1 | U(1)Y coupling constant |
| g_s | F | | Eq. 10 | 1.21978 | | G | QCD, 1 | Strong coupling constant |
| v | F | | Eq. 11 | 246.221 | | | QED, -1 | Higgs VEV |
| λ | F | | Eq. 12 | 0.118764 | | lam | QED, 2 | Higgs quartic coupling |
| μ | F | | Eq. 13 | 84.8528 | | | | Coefficient of the quadratic piece of the Higgs potential |
| yl | F | f | Eq. 14 | $y^l_1 \rightarrow 0.$ $y^l_2 \rightarrow 0.$ $y^l_3 \rightarrow 0.0102065$ | | $y^l_1 \rightarrow ye$ $y^l_2 \rightarrow ym$ $y^l_3 \rightarrow ytau$ | QED, 1 | Lepton Yukawa coupling |
| yu | F | f | Eq. 15 | $y^u_1 \rightarrow 0.$ $y^u_2 \rightarrow 0.$ $y^u_3 \rightarrow 0.987914$ | | $y^u_1 \rightarrow yup$ $y^u_2 \rightarrow yc$ $y^u_3 \rightarrow yt$ | QED, 1 | U-quark Yukawa coupling |
| yd | F | f | Eq. 16 | $y^d_1 \rightarrow 0.$ $y^d_2 \rightarrow 0.$ $y^d_3 \rightarrow 0.0269953$ | | $y^d_1 \rightarrow ydo$ $y^d_2 \rightarrow ys$ $y^d_3 \rightarrow yb$ | QED, 1 | D-quark Yukawa coupling |
| CKM | F | f, f | Eq. 17 | CKM _{1,1} \rightarrow 0.97418 CKM _{1,2} \rightarrow 0.225773 CKM _{1,3} \rightarrow 0. CKM _{2,1} \rightarrow -0.225773 CKM _{2,2} \rightarrow 0.97418 CKM _{2,3} \rightarrow 0. CKM _{3,1} \rightarrow 0. CKM _{3,2} \rightarrow 0. CKM _{3,3} \rightarrow 1. | | | | CKM-Matrix |

Table 12: Details of internal parameters. The headers are as follows: P = parameter, C = complex, I = Indices, V = value, NV = numerical value, D = definition, PN = parameter name, and IO = interaction order.

in Tables 12, 13, 14. The values and definitions of the internal parameters will be written below.

$$\alpha_{EW} = \frac{1}{\alpha_{EWM1}} \quad (2)$$

$$M_W = \sqrt{\frac{MZ^2}{2} + \sqrt{\frac{MZ^4}{4} - \frac{MZ^2\pi\alpha_{EW}}{\sqrt{2}G_f}}} \quad (3)$$

$$sw2 = 1 - \frac{M_W^2}{MZ^2} \quad (4)$$

| P | C | I | V | NV | D | PN | IO | Description |
|------|---|------|--------|--|---|----|--------|-------------|
| LQQR | T | f, f | Eq. 18 | $LQQR_{1,1} \rightarrow 0.1 + 0.I$ $LQQR_{1,2} \rightarrow 0.$ $LQQR_{1,3} \rightarrow 0.$ $LQQR_{1,2} \rightarrow 0.$ $LQQR_{2,2} \rightarrow 0.1 + 0.I$ $LQQR_{2,3} \rightarrow 0.$ $LQQR_{1,3} \rightarrow 0.$ $LQQR_{2,3} \rightarrow 0.$ $LQQR_{3,3} \rightarrow 0.1 + 0.I$ | | | QCD, 1 | |
| LUDL | T | f, f | Eq. 19 | $LUDL_{1,1} \rightarrow 0.1 + 0.I$ $LUDL_{1,2} \rightarrow 0.$ $LUDL_{1,3} \rightarrow 0.$ $LUDL_{1,2} \rightarrow 0.$ $LUDL_{2,2} \rightarrow 0.1 + 0.I$ $LUDL_{2,3} \rightarrow 0.$ $LUDL_{1,3} \rightarrow 0.$ $LUDL_{2,3} \rightarrow 0.$ $LUDL_{3,3} \rightarrow 0.1 + 0.I$ | | | QCD, 1 | |
| LUUL | T | f, f | Eq. 20 | $LUUL_{1,1} \rightarrow 0.1 + 0.I$ $LUUL_{1,2} \rightarrow 0.$ $LUUL_{1,3} \rightarrow 0.$ $LUUL_{1,2} \rightarrow 0.$ $LUUL_{2,2} \rightarrow 0.1 + 0.I$ $LUUL_{2,3} \rightarrow 0.$ $LUUL_{1,3} \rightarrow 0.$ $LUUL_{2,3} \rightarrow 0.$ $LUUL_{3,3} \rightarrow 0.1 + 0.I$ | | | QCD, 1 | |
| LDDL | T | f, f | Eq. 21 | $LDDL_{1,1} \rightarrow 0.1 + 0.I$ $LDDL_{1,2} \rightarrow 0.$ $LDDL_{1,3} \rightarrow 0.$ $LDDL_{1,2} \rightarrow 0.$ $LDDL_{2,2} \rightarrow 0.1 + 0.I$ $LDDL_{2,3} \rightarrow 0.$ | | | QCD, 1 | |

Table 13: Details of internal parameters. The headers are as follows: P = parameter, C = complex, I = Indices, V = value, NV = numerical value, D = definition, PN = parameter name, and IO = interaction order.

| P | C | I | V | NV | D | PN | IO | Description |
|---|---|---|---|--|---|----|----|-------------|
| | | | | $LDDL_{1,3} \rightarrow 0.$ $LDDL_{2,3} \rightarrow 0.$ $LDDL_{3,3} \rightarrow 0.1 + 0.I$ | | | | |

Table 14: Details of internal parameters. The headers are as follows: P = parameter, C = complex, I = Indices, V = value, NV = numerical value, D = definition, PN = parameter name, and IO = interaction order.

$$e = 2\sqrt{\pi}\sqrt{\alpha_{EW}} \quad (5)$$

$$c_w = \sqrt{1 - s_w^2} \quad (6)$$

$$s_w = \sqrt{s_w^2} \quad (7)$$

$$g_w = \frac{e}{s_w} \quad (8)$$

$$g_1 = \frac{e}{c_w} \quad (9)$$

$$g_s = 2\sqrt{\pi}\sqrt{\alpha_s} \quad (10)$$

$$v = \frac{2M_W s_w}{e} \quad (11)$$

$$\lambda = \frac{MH^2}{2v^2} \quad (12)$$

$$\mu = \sqrt{v^2 \lambda} \quad (13)$$

$$\begin{aligned} y^l_1 &= \frac{\sqrt{2}y_{me}}{v} \\ y^l_2 &= \frac{\sqrt{2}y_{mm}}{v} \\ y^l_3 &= \frac{\sqrt{2}y_{m\tau}}{v} \end{aligned} \quad (14)$$

$$\begin{aligned} y^u_1 &= \frac{\sqrt{2}y_{mup}}{v} \\ y^u_2 &= \frac{\sqrt{2}y_{mc}}{v} \\ y^u_3 &= \frac{\sqrt{2}y_{mt}}{v} \end{aligned} \quad (15)$$

$$\begin{aligned} y^d_1 &= \frac{\sqrt{2}y_{mdo}}{v} \\ y^d_2 &= \frac{\sqrt{2}y_{ms}}{v} \\ y^d_3 &= \frac{\sqrt{2}y_{mb}}{v} \end{aligned} \quad (16)$$

$$\begin{aligned} \text{CKM}_{1,1} &= \text{Cos}[\theta_c] \\ \text{CKM}_{1,2} &= \text{Sin}[\theta_c] \\ \text{CKM}_{1,3} &= 0 \\ \text{CKM}_{2,1} &= -\text{Sin}[\theta_c] \\ \text{CKM}_{2,2} &= \text{Cos}[\theta_c] \\ \text{CKM}_{2,3} &= 0 \\ \text{CKM}_{3,1} &= 0 \\ \text{CKM}_{3,2} &= 0 \\ \text{CKM}_{3,3} &= 1 \end{aligned} \quad (17)$$

$$\text{LQQR}_{i,j} = i\text{LQQR}_{i,j} + \text{LQQR}_{i,j} \quad (18)$$

$$\text{LUDL}_{i,j} = i\text{LUDL}_{i,j} + \text{LUDL}_{i,j} \quad (19)$$

$$\text{LUUL}_{i,j} = i\text{LUUL}_{i,j} + \text{LUUL}_{i,j} \quad (20)$$

$$\text{LDDL}_{i,j} = i\text{LDDL}_{i,j} + \text{LDDL}_{i,j} \quad (21)$$

6 Vertices

In this section, we describe the vertices of our model implementation.

6.1 V_1

$$\begin{aligned}
 & \begin{pmatrix} H & 1 \\ H & 2 \\ H & 3 \\ H & 4 \end{pmatrix} && -6i\lambda \\
 & \begin{pmatrix} H & 1 \\ H & 2 \\ \phi & 3 \\ \phi & 4 \end{pmatrix} && -2i\lambda \\
 & \begin{pmatrix} \phi & 1 \\ \phi & 2 \\ \phi & 3 \\ \phi & 4 \end{pmatrix} && -6i\lambda \\
 & \begin{pmatrix} H & 1 \\ H & 2 \\ \text{phi2} & 3 \\ \text{phi2}^\dagger & 4 \end{pmatrix} && -2i\lambda \\
 & \begin{pmatrix} \phi & 1 \\ \phi & 2 \\ \text{phi2} & 3 \\ \text{phi2}^\dagger & 4 \end{pmatrix} && -2i\lambda \\
 & \begin{pmatrix} \text{phi2} & 1 \\ \text{phi2} & 2 \\ \text{phi2}^\dagger & 3 \\ \text{phi2}^\dagger & 4 \end{pmatrix} && -4i\lambda \\
 & \begin{pmatrix} H & 1 \\ H & 2 \\ H & 3 \end{pmatrix} && -6i\nu\lambda \\
 & \begin{pmatrix} H & 1 \\ \phi & 2 \\ \phi & 3 \end{pmatrix} && -2i\nu\lambda \\
 & \begin{pmatrix} H & 1 \\ \text{phi2} & 2 \\ \text{phi2}^\dagger & 3 \end{pmatrix} && -2i\nu\lambda \\
 & \begin{pmatrix} A & 1 \\ A & 2 \\ \text{phi2} & 3 \\ \text{phi2}^\dagger & 4 \end{pmatrix} && 2ie^2\eta_{\mu_1,\mu_2} \\
 & \begin{pmatrix} A & 1 \\ \text{phi2} & 2 \\ \text{phi2}^\dagger & 3 \end{pmatrix} && ie p_2^{\mu_1} - ie p_3^{\mu_1}
 \end{aligned}$$

$$\begin{aligned}
\begin{pmatrix} \text{ghA}^\dagger & 1 \\ \text{ghWm} & 2 \\ W & 3 \end{pmatrix} & i\epsilon p_2^{\mu_3} + i\epsilon p_3^{\mu_3} \\
\begin{pmatrix} \text{ghA}^\dagger & 1 \\ \text{ghWp} & 2 \\ W^\dagger & 3 \end{pmatrix} & -i\epsilon p_2^{\mu_3} - i\epsilon p_3^{\mu_3} \\
\begin{pmatrix} \text{ghWm}^\dagger & 1 \\ \text{ghA} & 2 \\ \text{phi2}^\dagger & 3 \end{pmatrix} & eM_W \\
\begin{pmatrix} \text{ghWm}^\dagger & 1 \\ \text{ghA} & 2 \\ W^\dagger & 3 \end{pmatrix} & i\epsilon p_2^{\mu_3} + i\epsilon p_3^{\mu_3} \\
\begin{pmatrix} \text{ghWm}^\dagger & 1 \\ \text{ghWm} & 2 \\ H & 3 \end{pmatrix} & -\frac{i\epsilon M_W}{2s_w} \\
\begin{pmatrix} \text{ghWm}^\dagger & 1 \\ \text{ghWm} & 2 \\ \phi & 3 \end{pmatrix} & -\frac{eM_W}{2s_w} \\
\begin{pmatrix} A & 1 \\ \text{ghWm}^\dagger & 2 \\ \text{ghWm} & 3 \end{pmatrix} & -i\epsilon p_1^{\mu_1} - i\epsilon p_3^{\mu_1} \\
\begin{pmatrix} \text{ghWm}^\dagger & 1 \\ \text{ghWm} & 2 \\ Z & 3 \end{pmatrix} & -\frac{ic_w \epsilon p_2^{\mu_3}}{s_w} - \frac{ic_w \epsilon p_3^{\mu_3}}{s_w} \\
\begin{pmatrix} \text{ghWm}^\dagger & 1 \\ \text{ghZ} & 2 \\ \text{phi2}^\dagger & 3 \end{pmatrix} & \frac{c_w \epsilon M_W}{2s_w} - \frac{eM_W s_w}{2c_w} \\
\begin{pmatrix} \text{ghWm}^\dagger & 1 \\ \text{ghZ} & 2 \\ W^\dagger & 3 \end{pmatrix} & \frac{ic_w \epsilon p_2^{\mu_3}}{s_w} + \frac{ic_w \epsilon p_3^{\mu_3}}{s_w} \\
\begin{pmatrix} \text{ghWp}^\dagger & 1 \\ \text{ghA} & 2 \\ \text{phi2} & 3 \end{pmatrix} & -eM_W \\
\begin{pmatrix} \text{ghWp}^\dagger & 1 \\ \text{ghA} & 2 \\ W & 3 \end{pmatrix} & -i\epsilon p_2^{\mu_3} - i\epsilon p_3^{\mu_3}
\end{aligned}$$

$$\begin{aligned}
\begin{pmatrix} \text{ghWp}^\dagger & 1 \\ \text{ghWp} & 2 \\ H & 3 \end{pmatrix} & -\frac{i e M_W}{2 s_w} \\
\begin{pmatrix} \text{ghWp}^\dagger & 1 \\ \text{ghWp} & 2 \\ \phi & 3 \end{pmatrix} & \frac{e M_W}{2 s_w} \\
\begin{pmatrix} A & 1 \\ \text{ghWp}^\dagger & 2 \\ \text{ghWp} & 3 \end{pmatrix} & i e p_1^{\mu_1} + i e p_3^{\mu_1} \\
\begin{pmatrix} \text{ghWp}^\dagger & 1 \\ \text{ghWp} & 2 \\ Z & 3 \end{pmatrix} & \frac{i c_w e p_2^{\mu_3}}{s_w} + \frac{i c_w e p_3^{\mu_3}}{s_w} \\
\begin{pmatrix} \text{ghWp}^\dagger & 1 \\ \text{ghZ} & 2 \\ \text{phi2} & 3 \end{pmatrix} & -\frac{c_w e M_W}{2 s_w} + \frac{e M_W s_w}{2 c_w} \\
\begin{pmatrix} \text{ghWp}^\dagger & 1 \\ \text{ghZ} & 2 \\ W & 3 \end{pmatrix} & -\frac{i c_w e p_2^{\mu_3}}{s_w} - \frac{i c_w e p_3^{\mu_3}}{s_w} \\
\begin{pmatrix} \text{ghZ}^\dagger & 1 \\ \text{ghWm} & 2 \\ \text{phi2} & 3 \end{pmatrix} & \frac{e M_Z}{2 s_w} \\
\begin{pmatrix} \text{ghZ}^\dagger & 1 \\ \text{ghWm} & 2 \\ W & 3 \end{pmatrix} & \frac{i c_w e p_2^{\mu_3}}{s_w} + \frac{i c_w e p_3^{\mu_3}}{s_w} \\
\begin{pmatrix} \text{ghZ}^\dagger & 1 \\ \text{ghWp} & 2 \\ \text{phi2}^\dagger & 3 \end{pmatrix} & -\frac{e M_Z}{2 s_w} \\
\begin{pmatrix} \text{ghZ}^\dagger & 1 \\ \text{ghWp} & 2 \\ W^\dagger & 3 \end{pmatrix} & -\frac{i c_w e p_2^{\mu_3}}{s_w} - \frac{i c_w e p_3^{\mu_3}}{s_w} \\
\begin{pmatrix} \text{ghZ}^\dagger & 1 \\ \text{ghZ} & 2 \\ H & 3 \end{pmatrix} & -\frac{i e M_Z}{2 c_w s_w} \\
\begin{pmatrix} G & 1 \\ \text{ghG}^\dagger & 2 \\ \text{ghG} & 3 \end{pmatrix} & g_s f_{a_1, a_2, a_3} P_1^{\mu_1} + g_s f_{a_1, a_2, a_3} P_3^{\mu_1} \\
\begin{pmatrix} G & 1 \\ G & 2 \\ G & 3 \end{pmatrix} & g_s f_{a_1, a_2, a_3} P_1^{\mu_3} \eta_{\mu_1, \mu_2} - g_s f_{a_1, a_2, a_3} P_2^{\mu_3} \eta_{\mu_1, \mu_2} - g_s f_{a_1, a_2, a_3} P_1^{\mu_2} \eta_{\mu_1, \mu_3} + g_s f_{a_1, a_2, a_3} P_3^{\mu_2} \eta_{\mu_1, \mu_3} + \\
& g_s f_{a_1, a_2, a_3} P_2^{\mu_1} \eta_{\mu_2, \mu_3} - g_s f_{a_1, a_2, a_3} P_3^{\mu_1} \eta_{\mu_2, \mu_3}
\end{aligned}$$

| | |
|--|---|
| $\begin{pmatrix} G & 1 \\ G & 2 \\ G & 3 \\ G & 4 \end{pmatrix}$ | $ig_s^2 f_{a_1, a_3, a_1} f_{a_2, a_4, a_1} \eta_{\mu_1, \mu_4} \eta_{\mu_2, \mu_3} + ig_s^2 f_{a_1, a_2, a_1} f_{a_3, a_4, a_1} \eta_{\mu_1, \mu_4} \eta_{\mu_2, \mu_3} + ig_s^2 f_{a_1, a_4, a_1} f_{a_2, a_3, a_1} \eta_{\mu_1, \mu_3} \eta_{\mu_2, \mu_4} - ig_s^2 f_{a_1, a_2, a_1} f_{a_3, a_4, a_1} \eta_{\mu_1, \mu_3} \eta_{\mu_2, \mu_4} - ig_s^2 f_{a_1, a_4, a_1} f_{a_2, a_3, a_1} \eta_{\mu_1, \mu_2} \eta_{\mu_3, \mu_4} - ig_s^2 f_{a_1, a_3, a_1} f_{a_2, a_4, a_1} \eta_{\mu_1, \mu_2} \eta_{\mu_3, \mu_4}$ |
| $\begin{pmatrix} A & 1 \\ \text{six1} & 2 \\ \text{six1}^\dagger & 3 \end{pmatrix}$ | $\frac{1}{3} ic_w g_1 P_2^{\mu_1} \delta_{u_2, u_3} - \frac{1}{3} ic_w g_1 P_3^{\mu_1} \delta_{u_2, u_3}$ |
| $\begin{pmatrix} \bar{d}q & 1 \\ \text{six1} & 2 \\ \bar{u}q & 3 \end{pmatrix}$ | $2i\sqrt{2}K6\text{bar} [u_2, i_1, i_3] \text{LUDL}_{f_1, f_3} P_{-s_1, s_3} + 2i\sqrt{2}K6\text{bar} [u_2, i_1, i_3] \text{LQQR}_{f_1, f_3} P_{+s_1, s_3}$ |
| $\begin{pmatrix} dq & 1 \\ \text{six1}^\dagger & 2 \\ uq & 3 \end{pmatrix}$ | $2i\sqrt{2}\text{LQQR}_{f_1, f_3} *K6 [u_2, i_1, i_3] P_{-s_1, s_3} + 2i\sqrt{2}\text{LUDL}_{f_1, f_3} *K6 [u_2, i_1, i_3] P_{+s_1, s_3}$ |
| $\begin{pmatrix} H & 1 \\ H & 2 \\ \text{six1} & 3 \\ \text{six1}^\dagger & 4 \end{pmatrix}$ | $i\text{LHS1}\delta_{u_3, u_4}$ |
| $\begin{pmatrix} \phi & 1 \\ \phi & 2 \\ \text{six1} & 3 \\ \text{six1}^\dagger & 4 \end{pmatrix}$ | $i\text{LHS1}\delta_{u_3, u_4}$ |
| $\begin{pmatrix} \text{phi2} & 1 \\ \text{phi2}^\dagger & 2 \\ \text{six1} & 3 \\ \text{six1}^\dagger & 4 \end{pmatrix}$ | $i\text{LHS1}\delta_{u_3, u_4}$ |
| $\begin{pmatrix} H & 1 \\ \text{six1} & 2 \\ \text{six1}^\dagger & 3 \end{pmatrix}$ | $i\text{LHS1}v\delta_{u_2, u_3}$ |
| $\begin{pmatrix} A & 1 \\ A & 2 \\ \text{six1} & 3 \\ \text{six1}^\dagger & 4 \end{pmatrix}$ | $\frac{2}{9} ic_w^2 g_1^2 \delta_{u_3, u_4} \eta_{\mu_1, \mu_2}$ |
| $\begin{pmatrix} \text{six1} & 1 \\ \text{six1} & 2 \\ \text{six1}^\dagger & 3 \\ \text{six1}^\dagger & 4 \end{pmatrix}$ | $2i\text{LSS11}\delta_{u_1, u_4} \delta_{u_2, u_3} + 2i\text{LSS11}\delta_{u_1, u_3} \delta_{u_2, u_4}$ |
| $\begin{pmatrix} A & 1 \\ \text{six2} & 2 \\ \text{six2}^\dagger & 3 \end{pmatrix}$ | $-\frac{2}{3} ic_w g_1 P_2^{\mu_1} \delta_{u_2, u_3} + \frac{2}{3} ic_w g_1 P_3^{\mu_1} \delta_{u_2, u_3}$ |
| $\begin{pmatrix} \bar{d}q & 1 \\ \bar{d}q & 2 \\ \text{six2} & 3 \end{pmatrix}$ | $4i\sqrt{2}K6\text{bar} [u_3, i_1, i_2] \text{LDDL}_{f_1, f_2} P_{-s_1, s_2}$ |
| $\begin{pmatrix} dq & 1 \\ dq & 2 \\ \text{six2}^\dagger & 3 \end{pmatrix}$ | $4i\sqrt{2}\text{LDDL}_{f_1, f_2} *K6 [u_3, i_1, i_2] P_{+s_1, s_2}$ |

$$\begin{array}{l}
\begin{pmatrix} H & 1 \\ H & 2 \\ \text{six2} & 3 \\ \text{six2}^\dagger & 4 \end{pmatrix} \\
\begin{pmatrix} \phi & 1 \\ \phi & 2 \\ \text{six2} & 3 \\ \text{six2}^\dagger & 4 \end{pmatrix} \\
\begin{pmatrix} \text{phi2} & 1 \\ \text{phi2}^\dagger & 2 \\ \text{six2} & 3 \\ \text{six2}^\dagger & 4 \end{pmatrix} \\
\begin{pmatrix} H & 1 \\ \text{six2} & 2 \\ \text{six2}^\dagger & 3 \end{pmatrix} \\
\begin{pmatrix} A & 1 \\ A & 2 \\ \text{six2} & 3 \\ \text{six2}^\dagger & 4 \end{pmatrix} \\
\begin{pmatrix} \text{six1} & 1 \\ \text{six1}^\dagger & 2 \\ \text{six2} & 3 \\ \text{six2}^\dagger & 4 \end{pmatrix} \\
\begin{pmatrix} \text{six2} & 1 \\ \text{six2} & 2 \\ \text{six2}^\dagger & 3 \\ \text{six2}^\dagger & 4 \end{pmatrix} \\
\begin{pmatrix} A & 1 \\ \text{six3} & 2 \\ \text{six3}^\dagger & 3 \end{pmatrix} \\
\begin{pmatrix} \text{six3} & 1 \\ \bar{u}q & 2 \\ \bar{u}q & 3 \end{pmatrix} \\
\begin{pmatrix} \text{six3}^\dagger & 1 \\ uq & 2 \\ uq & 3 \end{pmatrix} \\
\begin{pmatrix} H & 1 \\ H & 2 \\ \text{six3} & 3 \\ \text{six3}^\dagger & 4 \end{pmatrix} \\
\begin{pmatrix} \phi & 1 \\ \phi & 2 \\ \text{six3} & 3 \\ \text{six3}^\dagger & 4 \end{pmatrix}
\end{array}
\begin{array}{l}
i\text{LHS2}\delta_{u_3, u_4} \\
i\text{LHS2}\delta_{u_3, u_4} \\
i\text{LHS2}\delta_{u_3, u_4} \\
i\text{LHS2}v\delta_{u_2, u_3} \\
\frac{8}{9}ic_w^2g_1^2\delta_{u_3, u_4}\eta_{\mu_1, \mu_2} \\
i\text{LSS122}\delta_{u_1, u_4}\delta_{u_2, u_3} + i\text{LSS121}\delta_{u_1, u_2}\delta_{u_3, u_4} \\
2i\text{LSS22}\delta_{u_1, u_4}\delta_{u_2, u_3} + 2i\text{LSS22}\delta_{u_1, u_3}\delta_{u_2, u_4} \\
\frac{4}{3}ic_wg_1P_2^{\mu_1}\delta_{u_2, u_3} - \frac{4}{3}ic_wg_1P_3^{\mu_1}\delta_{u_2, u_3} \\
4i\sqrt{2}K6\text{bar}[u_1, i_2, i_3]LUUL_{f_2, f_3}P_{-s_2, s_3} \\
4i\sqrt{2}LUUL_{f_2, f_3} * K6[u_1, i_2, i_3]P_{+s_2, s_3} \\
i\text{LHS3}\delta_{u_3, u_4} \\
i\text{LHS3}\delta_{u_3, u_4}
\end{array}$$

$$\begin{aligned}
& \begin{pmatrix} \text{phi2} & 1 \\ \text{phi2}^\dagger & 2 \\ \text{six3} & 3 \\ \text{six3}^\dagger & 4 \end{pmatrix} & i\text{LHS3}\delta_{u_3, u_4} \\
& \begin{pmatrix} H & 1 \\ \text{six3} & 2 \\ \text{six3}^\dagger & 3 \end{pmatrix} & i\text{LHS3}v\delta_{u_2, u_3} \\
& \begin{pmatrix} A & 1 \\ A & 2 \\ \text{six3} & 3 \\ \text{six3}^\dagger & 4 \end{pmatrix} & \frac{32}{9}i c_w^2 g_1^2 \delta_{u_3, u_4} \eta_{\mu_1, \mu_2} \\
& \begin{pmatrix} \text{six1} & 1 \\ \text{six1}^\dagger & 2 \\ \text{six3} & 3 \\ \text{six3}^\dagger & 4 \end{pmatrix} & i\text{LSS132}\delta_{u_1, u_4} \delta_{u_2, u_3} + i\text{LSS131}\delta_{u_1, u_2} \delta_{u_3, u_4} \\
& \begin{pmatrix} \text{six2} & 1 \\ \text{six2}^\dagger & 2 \\ \text{six3} & 3 \\ \text{six3}^\dagger & 4 \end{pmatrix} & i\text{LSS232}\delta_{u_1, u_4} \delta_{u_2, u_3} + i\text{LSS231}\delta_{u_1, u_2} \delta_{u_3, u_4} \\
& \begin{pmatrix} \text{six3} & 1 \\ \text{six3} & 2 \\ \text{six3}^\dagger & 3 \\ \text{six3}^\dagger & 4 \end{pmatrix} & 2i\text{LSS33}\delta_{u_1, u_4} \delta_{u_2, u_3} + 2i\text{LSS33}\delta_{u_1, u_3} \delta_{u_2, u_4} \\
& \begin{pmatrix} \text{dq} & 1 \\ \bar{\text{dq}} & 2 \\ G & 3 \end{pmatrix} & i g_s \gamma_{s_2, s_1}^{\mu_3} \delta_{f_1, f_2} T_{i_2, i_1}^{a_3} \\
& \begin{pmatrix} G & 1 \\ \text{uq} & 2 \\ \bar{\text{uq}} & 3 \end{pmatrix} & i g_s \gamma_{s_3, s_2}^{\mu_1} \delta_{f_2, f_3} T_{i_3, i_2}^{a_1} \\
& \begin{pmatrix} G & 1 \\ \text{six1} & 2 \\ \text{six1}^\dagger & 3 \end{pmatrix} & i g_s p_2^{\mu_1} T_{u_3, u_2}^{a_1} - i g_s p_3^{\mu_1} T_{u_3, u_2}^{a_1} \\
& \begin{pmatrix} A & 1 \\ G & 2 \\ \text{six1} & 3 \\ \text{six1}^\dagger & 4 \end{pmatrix} & \frac{2}{3} i c_w g_1 g_s \eta_{\mu_1, \mu_2} T_{u_4, u_3}^{a_2} \\
& \begin{pmatrix} G & 1 \\ G & 2 \\ \text{six1} & 3 \\ \text{six1}^\dagger & 4 \end{pmatrix} & i g_s^2 \eta_{\mu_1, \mu_2} T_{a_1, u_3}^{a_1} T_{u_4, a_1}^{a_2} + i g_s^2 \eta_{\mu_1, \mu_2} T_{u_4, a_1}^{a_1} T_{a_1, u_3}^{a_2} \\
& \begin{pmatrix} G & 1 \\ \text{six2} & 2 \\ \text{six2}^\dagger & 3 \end{pmatrix} & i g_s p_2^{\mu_1} T_{u_3, u_2}^{a_1} - i g_s p_3^{\mu_1} T_{u_3, u_2}^{a_1} \\
& \begin{pmatrix} A & 1 \\ G & 2 \\ \text{six2} & 3 \\ \text{six2}^\dagger & 4 \end{pmatrix} & -\frac{4}{3} i c_w g_1 g_s \eta_{\mu_1, \mu_2} T_{u_4, u_3}^{a_2}
\end{aligned}$$

$$\begin{aligned}
& \begin{pmatrix} G & 1 \\ G & 2 \\ \text{six}2 & 3 \\ \text{six}2^\dagger & 4 \end{pmatrix} & ig_s^2 \eta_{\mu_1, \mu_2} T_{6_{a1, u_3}}^{a_1} T_{6_{u_4, a1}}^{a_2} + ig_s^2 \eta_{\mu_1, \mu_2} T_{6_{u_4, a1}}^{a_1} T_{6_{a1, u_3}}^{a_2} \\
& \begin{pmatrix} G & 1 \\ \text{six}3 & 2 \\ \text{six}3^\dagger & 3 \end{pmatrix} & ig_s P_2^{\mu_1} T_{6_{u_3, u_2}}^{a_1} - ig_s P_3^{\mu_1} T_{6_{u_3, u_2}}^{a_1} \\
& \begin{pmatrix} A & 1 \\ G & 2 \\ \text{six}3 & 3 \\ \text{six}3^\dagger & 4 \end{pmatrix} & \frac{8}{3} i c_w g_1 g_s \eta_{\mu_1, \mu_2} T_{6_{u_4, u_3}}^{a_2} \\
& \begin{pmatrix} G & 1 \\ G & 2 \\ \text{six}3 & 3 \\ \text{six}3^\dagger & 4 \end{pmatrix} & ig_s^2 \eta_{\mu_1, \mu_2} T_{6_{a1, u_3}}^{a_1} T_{6_{u_4, a1}}^{a_2} + ig_s^2 \eta_{\mu_1, \mu_2} T_{6_{u_4, a1}}^{a_1} T_{6_{a1, u_3}}^{a_2} \\
& \begin{pmatrix} A & 1 \\ H & 2 \\ \text{phi}2^\dagger & 3 \\ W & 4 \end{pmatrix} & -\frac{e^2 \eta_{\mu_1, \mu_4}}{2s_w} \\
& \begin{pmatrix} A & 1 \\ \phi & 2 \\ \text{phi}2^\dagger & 3 \\ W & 4 \end{pmatrix} & -\frac{ie^2 \eta_{\mu_1, \mu_4}}{2s_w} \\
& \begin{pmatrix} A & 1 \\ \text{phi}2^\dagger & 2 \\ W & 3 \end{pmatrix} & -\frac{e^2 v \eta_{\mu_1, \mu_3}}{2s_w} \\
& \begin{pmatrix} H & 1 \\ \text{phi}2^\dagger & 2 \\ W & 3 \end{pmatrix} & -\frac{e p_1^{\mu_3}}{2s_w} + \frac{e p_2^{\mu_3}}{2s_w} \\
& \begin{pmatrix} \phi & 1 \\ \text{phi}2^\dagger & 2 \\ W & 3 \end{pmatrix} & -\frac{ie p_1^{\mu_3}}{2s_w} + \frac{ie p_2^{\mu_3}}{2s_w} \\
& \begin{pmatrix} A & 1 \\ W & 2 \\ W^\dagger & 3 \end{pmatrix} & -ig_w s_w P_1^{\mu_3} \eta_{\mu_1, \mu_2} + ig_w s_w P_2^{\mu_3} \eta_{\mu_1, \mu_2} + ig_w s_w P_1^{\mu_2} \eta_{\mu_1, \mu_3} - ig_w s_w P_3^{\mu_2} \eta_{\mu_1, \mu_3} - ig_w s_w P_2^{\mu_1} \eta_{\mu_2, \mu_3} + ig_w s_w P_3^{\mu_1} \eta_{\mu_2, \mu_3} \\
& \begin{pmatrix} A & 1 \\ H & 2 \\ \text{phi}2 & 3 \\ W^\dagger & 4 \end{pmatrix} & \frac{e^2 \eta_{\mu_1, \mu_4}}{2s_w} \\
& \begin{pmatrix} A & 1 \\ \phi & 2 \\ \text{phi}2 & 3 \\ W^\dagger & 4 \end{pmatrix} & -\frac{ie^2 \eta_{\mu_1, \mu_4}}{2s_w} \\
& \begin{pmatrix} A & 1 \\ \text{phi}2 & 2 \\ W^\dagger & 3 \end{pmatrix} & \frac{e^2 v \eta_{\mu_1, \mu_3}}{2s_w}
\end{aligned}$$

$$\begin{aligned}
& \begin{pmatrix} H & 1 \\ \text{phi2} & 2 \\ W^\dagger & 3 \end{pmatrix} & -\frac{ep_1^{\mu_3}}{2s_w} + \frac{ep_2^{\mu_3}}{2s_w} \\
& \begin{pmatrix} \phi & 1 \\ \text{phi2} & 2 \\ W^\dagger & 3 \end{pmatrix} & \frac{iep_1^{\mu_3}}{2s_w} - \frac{iep_2^{\mu_3}}{2s_w} \\
& \begin{pmatrix} H & 1 \\ H & 2 \\ W & 3 \\ W^\dagger & 4 \end{pmatrix} & \frac{ie^2 \eta_{\mu_3, \mu_4}}{2s_w^2} \\
& \begin{pmatrix} \phi & 1 \\ \phi & 2 \\ W & 3 \\ W^\dagger & 4 \end{pmatrix} & \frac{ie^2 \eta_{\mu_3, \mu_4}}{2s_w^2} \\
& \begin{pmatrix} \text{phi2} & 1 \\ \text{phi2}^\dagger & 2 \\ W & 3 \\ W^\dagger & 4 \end{pmatrix} & \frac{ie^2 \eta_{\mu_3, \mu_4}}{2s_w^2} \\
& \begin{pmatrix} H & 1 \\ W & 2 \\ W^\dagger & 3 \end{pmatrix} & \frac{ie^2 v \eta_{\mu_2, \mu_3}}{2s_w^2} \\
& \begin{pmatrix} A & 1 \\ A & 2 \\ W & 3 \\ W^\dagger & 4 \end{pmatrix} & ig_w^2 s_w^2 \eta_{\mu_1, \mu_4} \eta_{\mu_2, \mu_3} + ig_w^2 s_w^2 \eta_{\mu_1, \mu_3} \eta_{\mu_2, \mu_4} - 2ig_w^2 s_w^2 \eta_{\mu_1, \mu_2} \eta_{\mu_3, \mu_4} \\
& \begin{pmatrix} W & 1 \\ W^\dagger & 2 \\ Z & 3 \end{pmatrix} & -ic_w g_w p_1^{\mu_3} \eta_{\mu_1, \mu_2} + ic_w g_w p_2^{\mu_3} \eta_{\mu_1, \mu_2} + ic_w g_w p_1^{\mu_2} \eta_{\mu_1, \mu_3} - ic_w g_w p_3^{\mu_2} \eta_{\mu_1, \mu_3} - ic_w g_w p_2^{\mu_1} \eta_{\mu_2, \mu_3} + ic_w g_w p_3^{\mu_1} \eta_{\mu_2, \mu_3} \\
& \begin{pmatrix} W & 1 \\ W & 2 \\ W^\dagger & 3 \\ W^\dagger & 4 \end{pmatrix} & -ig_w^2 \eta_{\mu_1, \mu_4} \eta_{\mu_2, \mu_3} - ig_w^2 \eta_{\mu_1, \mu_3} \eta_{\mu_2, \mu_4} + 2ig_w^2 \eta_{\mu_1, \mu_2} \eta_{\mu_3, \mu_4} \\
& \begin{pmatrix} dq & 1 \\ \text{phi2} & 2 \\ \bar{u}q & 3 \end{pmatrix} & -\text{CKM}_{f_3, f_1} \delta_{i_1, i_3} P_{+s_3, s_1} y_{f_1}^d + \text{CKM}_{f_3, f_1} \delta_{i_1, i_3} P_{-s_3, s_1} y_{f_3}^u \\
& \begin{pmatrix} \bar{d}q & 1 \\ \text{phi2}^\dagger & 2 \\ uq & 3 \end{pmatrix} & \text{CKM}_{f_3, f_1}^* \delta_{i_1, i_3} P_{-s_1, s_3} y_{f_1}^d - \text{CKM}_{f_3, f_1}^* \delta_{i_1, i_3} P_{+s_1, s_3} y_{f_3}^u \\
& \begin{pmatrix} dq & 1 \\ \bar{d}q & 2 \\ H & 3 \end{pmatrix} & -\frac{i\delta_{i_1, i_2} \delta_{f_1, f_2} \delta_{s_2, s_1} y_{f_1}^d}{\sqrt{2}} \\
& \begin{pmatrix} dq & 1 \\ \bar{d}q & 2 \\ \phi & 3 \end{pmatrix} & \frac{\gamma_{s_2, s_1} \delta_{i_1, i_2} \delta_{f_1, f_2} y_{f_1}^d}{\sqrt{2}}
\end{aligned}$$

$$\begin{aligned}
& \begin{pmatrix} H & 1 \\ l & 2 \\ \bar{l} & 3 \end{pmatrix} & -\frac{i\delta_{f_2, f_3} \delta_{s_3, s_2} y^l_{f_2}}{\sqrt{2}} \\
& \begin{pmatrix} l & 1 \\ \bar{l} & 2 \\ \phi & 3 \end{pmatrix} & \frac{\gamma_{s_2, s_1} \delta_{f_1, f_2} y^l_{f_1}}{\sqrt{2}} \\
& \begin{pmatrix} l & 1 \\ \text{phi2} & 2 \\ \bar{vl} & 3 \end{pmatrix} & -\delta_{f_1, f_3} P_{+s_3, s_1} y^l_{f_1} \\
& \begin{pmatrix} \bar{l} & 1 \\ \text{phi2}^\dagger & 2 \\ vl & 3 \end{pmatrix} & \delta_{f_1, f_3} P_{-s_1, s_3} y^l_{f_1} \\
& \begin{pmatrix} H & 1 \\ \text{uq} & 2 \\ \bar{\text{uq}} & 3 \end{pmatrix} & -\frac{i\delta_{i_2, i_3} \delta_{f_2, f_3} \delta_{s_3, s_2} y^u_{f_2}}{\sqrt{2}} \\
& \begin{pmatrix} \phi & 1 \\ \text{uq} & 2 \\ \bar{\text{uq}} & 3 \end{pmatrix} & -\frac{\gamma_{s_3, s_2} \delta_{i_2, i_3} \delta_{f_2, f_3} y^u_{f_2}}{\sqrt{2}} \\
& \begin{pmatrix} A & 1 \\ \text{phi2} & 2 \\ \text{phi2}^\dagger & 3 \\ Z & 4 \end{pmatrix} & \frac{ic_w e^2 \eta_{\mu_1, \mu_4}}{s_w} - \frac{ie^2 s_w \eta_{\mu_1, \mu_4}}{c_w} \\
& \begin{pmatrix} H & 1 \\ \phi & 2 \\ Z & 3 \end{pmatrix} & -\frac{c_w e p_1^{\mu_3}}{2s_w} - \frac{e s_w p_1^{\mu_3}}{2c_w} + \frac{c_w e p_2^{\mu_3}}{2s_w} + \frac{e s_w p_2^{\mu_3}}{2c_w} \\
& \begin{pmatrix} \text{phi2} & 1 \\ \text{phi2}^\dagger & 2 \\ Z & 3 \end{pmatrix} & \frac{ic_w e p_1^{\mu_3}}{2s_w} - \frac{e s_w p_1^{\mu_3}}{2c_w} - \frac{ic_w e p_2^{\mu_3}}{2s_w} + \frac{e s_w p_2^{\mu_3}}{2c_w} \\
& \begin{pmatrix} \text{six1} & 1 \\ \text{six1}^\dagger & 2 \\ Z & 3 \end{pmatrix} & -\frac{1}{3} i g_1 s_w p_1^{\mu_3} \delta_{u_1, u_2} + \frac{1}{3} i g_1 s_w p_2^{\mu_3} \delta_{u_1, u_2} \\
& \begin{pmatrix} A & 1 \\ \text{six1} & 2 \\ \text{six1}^\dagger & 3 \\ Z & 4 \end{pmatrix} & -\frac{2}{9} i c_w g_1^2 s_w \delta_{u_2, u_3} \eta_{\mu_1, \mu_4} \\
& \begin{pmatrix} \text{six2} & 1 \\ \text{six2}^\dagger & 2 \\ Z & 3 \end{pmatrix} & \frac{2}{3} i g_1 s_w p_1^{\mu_3} \delta_{u_1, u_2} - \frac{2}{3} i g_1 s_w p_2^{\mu_3} \delta_{u_1, u_2} \\
& \begin{pmatrix} A & 1 \\ \text{six2} & 2 \\ \text{six2}^\dagger & 3 \\ Z & 4 \end{pmatrix} & -\frac{8}{9} i c_w g_1^2 s_w \delta_{u_2, u_3} \eta_{\mu_1, \mu_4} \\
& \begin{pmatrix} \text{six3} & 1 \\ \text{six3}^\dagger & 2 \\ Z & 3 \end{pmatrix} & -\frac{4}{3} i g_1 s_w p_1^{\mu_3} \delta_{u_1, u_2} + \frac{4}{3} i g_1 s_w p_2^{\mu_3} \delta_{u_1, u_2}
\end{aligned}$$

$$\begin{aligned}
& \begin{pmatrix} A & 1 \\ \text{six}3 & 2 \\ \text{six}3^\dagger & 3 \\ Z & 4 \end{pmatrix} & -\frac{32}{9}i c_w g_1^2 s_w \delta_{u_2, u_3} \eta_{\mu_1, \mu_4} \\
& \begin{pmatrix} G & 1 \\ \text{six}1 & 2 \\ \text{six}1^\dagger & 3 \\ Z & 4 \end{pmatrix} & -\frac{2}{3}i g_1 g_s s_w \eta_{\mu_1, \mu_4} T_{6_{u_3, u_2}}^{a_1} \\
& \begin{pmatrix} G & 1 \\ \text{six}2 & 2 \\ \text{six}2^\dagger & 3 \\ Z & 4 \end{pmatrix} & \frac{4}{3}i g_1 g_s s_w \eta_{\mu_1, \mu_4} T_{6_{u_3, u_2}}^{a_1} \\
& \begin{pmatrix} G & 1 \\ \text{six}3 & 2 \\ \text{six}3^\dagger & 3 \\ Z & 4 \end{pmatrix} & -\frac{8}{3}i g_1 g_s s_w \eta_{\mu_1, \mu_4} T_{6_{u_3, u_2}}^{a_1} \\
& \begin{pmatrix} H & 1 \\ \text{phi}2^\dagger & 2 \\ W & 3 \\ Z & 4 \end{pmatrix} & \frac{e^2 \eta_{\mu_3, \mu_4}}{2c_w} \\
& \begin{pmatrix} \phi & 1 \\ \text{phi}2^\dagger & 2 \\ W & 3 \\ Z & 4 \end{pmatrix} & \frac{ie^2 \eta_{\mu_3, \mu_4}}{2c_w} \\
& \begin{pmatrix} \text{phi}2^\dagger & 1 \\ W & 2 \\ Z & 3 \end{pmatrix} & \frac{e^2 v \eta_{\mu_2, \mu_3}}{2c_w} \\
& \begin{pmatrix} H & 1 \\ \text{phi}2 & 2 \\ W^\dagger & 3 \\ Z & 4 \end{pmatrix} & -\frac{e^2 \eta_{\mu_3, \mu_4}}{2c_w} \\
& \begin{pmatrix} \phi & 1 \\ \text{phi}2 & 2 \\ W^\dagger & 3 \\ Z & 4 \end{pmatrix} & \frac{ie^2 \eta_{\mu_3, \mu_4}}{2c_w} \\
& \begin{pmatrix} \text{phi}2 & 1 \\ W^\dagger & 2 \\ Z & 3 \end{pmatrix} & -\frac{e^2 v \eta_{\mu_2, \mu_3}}{2c_w} \\
& \begin{pmatrix} A & 1 \\ W & 2 \\ W^\dagger & 3 \\ Z & 4 \end{pmatrix} & -2i c_w g_w^2 s_w \eta_{\mu_1, \mu_4} \eta_{\mu_2, \mu_3} + i c_w g_w^2 s_w \eta_{\mu_1, \mu_3} \eta_{\mu_2, \mu_4} + i c_w g_w^2 s_w \eta_{\mu_1, \mu_2} \eta_{\mu_3, \mu_4} \\
& \begin{pmatrix} H & 1 \\ H & 2 \\ Z & 3 \\ Z & 4 \end{pmatrix} & ie^2 \eta_{\mu_3, \mu_4} + \frac{i c_w^2 e^2 \eta_{\mu_3, \mu_4}}{2s_w^2} + \frac{ie^2 s_w^2 \eta_{\mu_3, \mu_4}}{2c_w^2}
\end{aligned}$$

$$\begin{aligned}
& \begin{pmatrix} \phi & 1 \\ \phi & 2 \\ Z & 3 \\ Z & 4 \end{pmatrix} && ie^2 \eta_{\mu_3, \mu_4} + \frac{ic_w^2 e^2 \eta_{\mu_3, \mu_4}}{2s_w^2} + \frac{ie^2 s_w^2 \eta_{\mu_3, \mu_4}}{2c_w^2} \\
& \begin{pmatrix} \text{phi2} & 1 \\ \text{phi2}^\dagger & 2 \\ Z & 3 \\ Z & 4 \end{pmatrix} && -ie^2 \eta_{\mu_3, \mu_4} + \frac{ic_w^2 e^2 \eta_{\mu_3, \mu_4}}{2s_w^2} + \frac{ie^2 s_w^2 \eta_{\mu_3, \mu_4}}{2c_w^2} \\
& \begin{pmatrix} H & 1 \\ Z & 2 \\ Z & 3 \end{pmatrix} && ie^2 v \eta_{\mu_2, \mu_3} + \frac{ic_w^2 e^2 v \eta_{\mu_2, \mu_3}}{2s_w^2} + \frac{ie^2 s_w^2 v \eta_{\mu_2, \mu_3}}{2c_w^2} \\
& \begin{pmatrix} \text{six1} & 1 \\ \text{six1}^\dagger & 2 \\ Z & 3 \\ Z & 4 \end{pmatrix} && \frac{2}{9} i g_1^2 s_w^2 \delta_{u_1, u_2} \eta_{\mu_3, \mu_4} \\
& \begin{pmatrix} \text{six2} & 1 \\ \text{six2}^\dagger & 2 \\ Z & 3 \\ Z & 4 \end{pmatrix} && \frac{8}{9} i g_1^2 s_w^2 \delta_{u_1, u_2} \eta_{\mu_3, \mu_4} \\
& \begin{pmatrix} \text{six3} & 1 \\ \text{six3}^\dagger & 2 \\ Z & 3 \\ Z & 4 \end{pmatrix} && \frac{32}{9} i g_1^2 s_w^2 \delta_{u_1, u_2} \eta_{\mu_3, \mu_4} \\
& \begin{pmatrix} W & 1 \\ W^\dagger & 2 \\ Z & 3 \\ Z & 4 \end{pmatrix} && ic_w^2 g_w^2 \eta_{\mu_1, \mu_4} \eta_{\mu_2, \mu_3} + ic_w^2 g_w^2 \eta_{\mu_1, \mu_3} \eta_{\mu_2, \mu_4} - 2ic_w^2 g_w^2 \eta_{\mu_1, \mu_2} \eta_{\mu_3, \mu_4} \\
& \begin{pmatrix} A & 1 \\ \text{dq} & 2 \\ \bar{\text{dq}} & 3 \end{pmatrix} && -\frac{1}{3} ie \gamma_{s_3, s_2}^{\mu_1} \delta_{i_2, i_3} \delta_{f_2, f_3} \\
& \begin{pmatrix} A & 1 \\ l & 2 \\ \bar{l} & 3 \end{pmatrix} && -ie \gamma_{s_3, s_2}^{\mu_1} \delta_{f_2, f_3} \\
& \begin{pmatrix} A & 1 \\ \text{uq} & 2 \\ \bar{\text{uq}} & 3 \end{pmatrix} && \frac{2}{3} ie \gamma_{s_3, s_2}^{\mu_1} \delta_{i_2, i_3} \delta_{f_2, f_3} \\
& \begin{pmatrix} l & 1 \\ \bar{\nu} l & 2 \\ W & 3 \end{pmatrix} && \frac{ie \delta_{f_1, f_2} \gamma^{\mu_3} \cdot P_{-s_2, s_1}}{\sqrt{2} s_w} \\
& \begin{pmatrix} \text{dq} & 1 \\ \bar{\text{uq}} & 2 \\ W & 3 \end{pmatrix} && \frac{ie \text{CKM}_{f_2, f_1} \delta_{i_1, i_2} \gamma^{\mu_3} \cdot P_{-s_2, s_1}}{\sqrt{2} s_w} \\
& \begin{pmatrix} \bar{l} & 1 \\ \nu l & 2 \\ W^\dagger & 3 \end{pmatrix} && \frac{ie \delta_{f_1, f_2} \gamma^{\mu_3} \cdot P_{-s_1, s_2}}{\sqrt{2} s_w}
\end{aligned}$$

$$\begin{pmatrix} \bar{d}q & 1 \\ uq & 2 \\ W^\dagger & 3 \end{pmatrix} \frac{ie\text{CKM}_{f_2, f_1} \delta_{i_1, i_2} \gamma^{\mu 3} \cdot P_{-s_1, s_2}}{\sqrt{2}s_w} \\
\begin{pmatrix} dq & 1 \\ \bar{d}q & 2 \\ Z & 3 \end{pmatrix} - \frac{ic_w e \delta_{i_1, i_2} \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{2s_w} - \frac{ies_w \delta_{i_1, i_2} \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{6c_w} + \frac{ies_w \delta_{i_1, i_2} \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{+s_2, s_1}}{3c_w} \\
\begin{pmatrix} l & 1 \\ \bar{l} & 2 \\ Z & 3 \end{pmatrix} - \frac{ic_w e \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{2s_w} + \frac{ies_w \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{2c_w} + \frac{ies_w \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{+s_2, s_1}}{c_w} \\
\begin{pmatrix} uq & 1 \\ \bar{u}q & 2 \\ Z & 3 \end{pmatrix} \frac{ic_w e \delta_{i_1, i_2} \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{2s_w} - \frac{ies_w \delta_{i_1, i_2} \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{6c_w} - \frac{2ies_w \delta_{i_1, i_2} \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{+s_2, s_1}}{3c_w} \\
\begin{pmatrix} vl & 1 \\ \bar{v}l & 2 \\ Z & 3 \end{pmatrix} \frac{ic_w e \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{2s_w} + \frac{ies_w \delta_{f_1, f_2} \gamma^{\mu 3} \cdot P_{-s_2, s_1}}{2c_w}
\end{pmatrix}$$

References

- [1] N. D. Christensen and C. Duhr, arXiv:0806.4194 [hep-ph].